

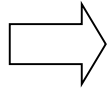
Extendable Toolchain for Automatic Compatibility Checks

OCL @ MODELS 2016

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Outline



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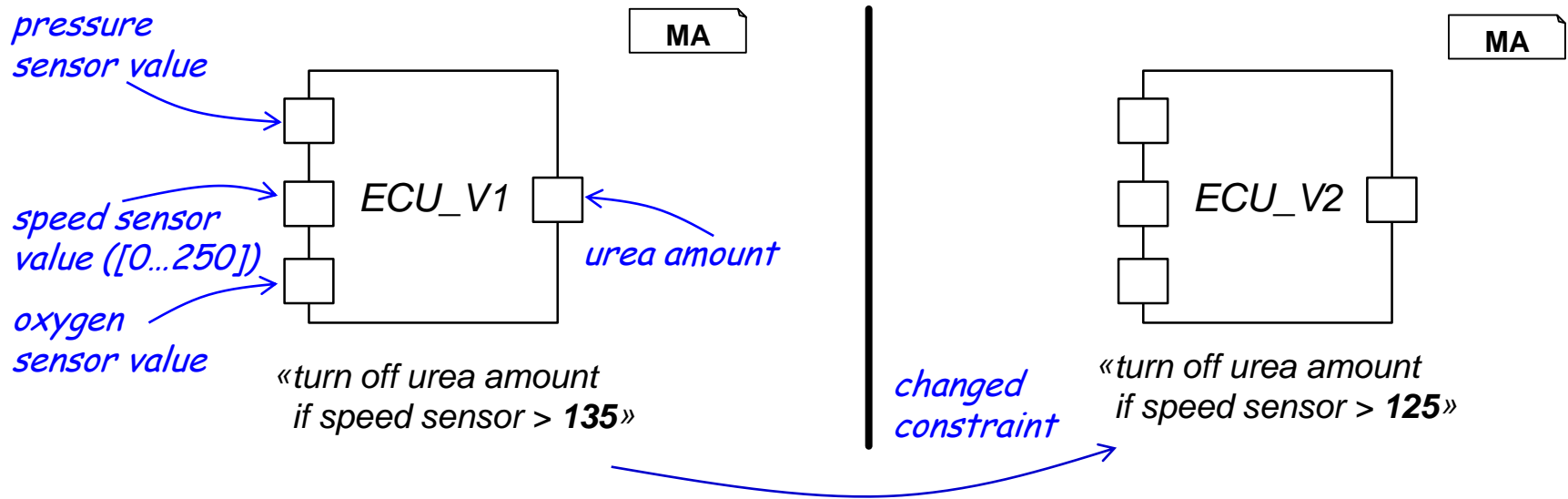
Conclusion

Motivation - General

- Automotive software has a dramatically increased number of software components
 - Example: Emissions control systems
 - They have **complex systems** with different HW / SW components
 - Various tools are used inside a development toolchain
- Vehicles will be continually improved
 - Existence of **evolution** and **variants** of function components
 - As well as **large** and **complex product line families**
- **Safety** of software components is very important in many areas (esp. automotive / aerospace / railway industry)
 - Safety-relevant software in the sense of ISO 26262
 - Automotive Safety Integrity Level (ASIL) classification

Motivation - Example

Automotive Emission Control System (simplified)



A developer team member is unsure if the new version can be used in the US and in Germany.

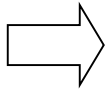
Varying regulations in different countries:

In **Germany** the emission control can be turned off if the speed is greater 120 km/h, whereas in the **US** it can be turned off if speed is greater 128 km/h.

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Structural Compatibility

- Component compatibility: **Structural compatibility** serves as a first indicator as it is an important prerequisite for **full compatibility**, which would also enclose **behavioral compatibility**.
- Compatibility of **different versions** and **variants** for **function components**
 - **V2 + V1**: V2 is **backward compatible**, V2 can replace V1.
 - **V2 – V1**: V2 is **forward compatible**, V2 can be replaced by V1.
 - **V2 0 V1**: V2 is **full compatible** to V1, both components can replace each other (have exactly the same behavior)

Requirements from Industry¹

- (1) Compatibility constraints should be defined in **comprehensive** and **concise** notation
- (2) Method should support **heterogeneous** C&C architecture **models**
- (3) **Developers** should be able to **modify** structural compatibility constraints at runtime
- (4) **Meaningful** and model related **error messages** for **engineers**
- (5) Genuine C&C model **files** should **not** be **modified**
- (6) Compatibility checking should be **easy** for **engineers**

¹http://spes2020.informatik.tu-muenchen.de/spes_xt-home.html

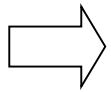
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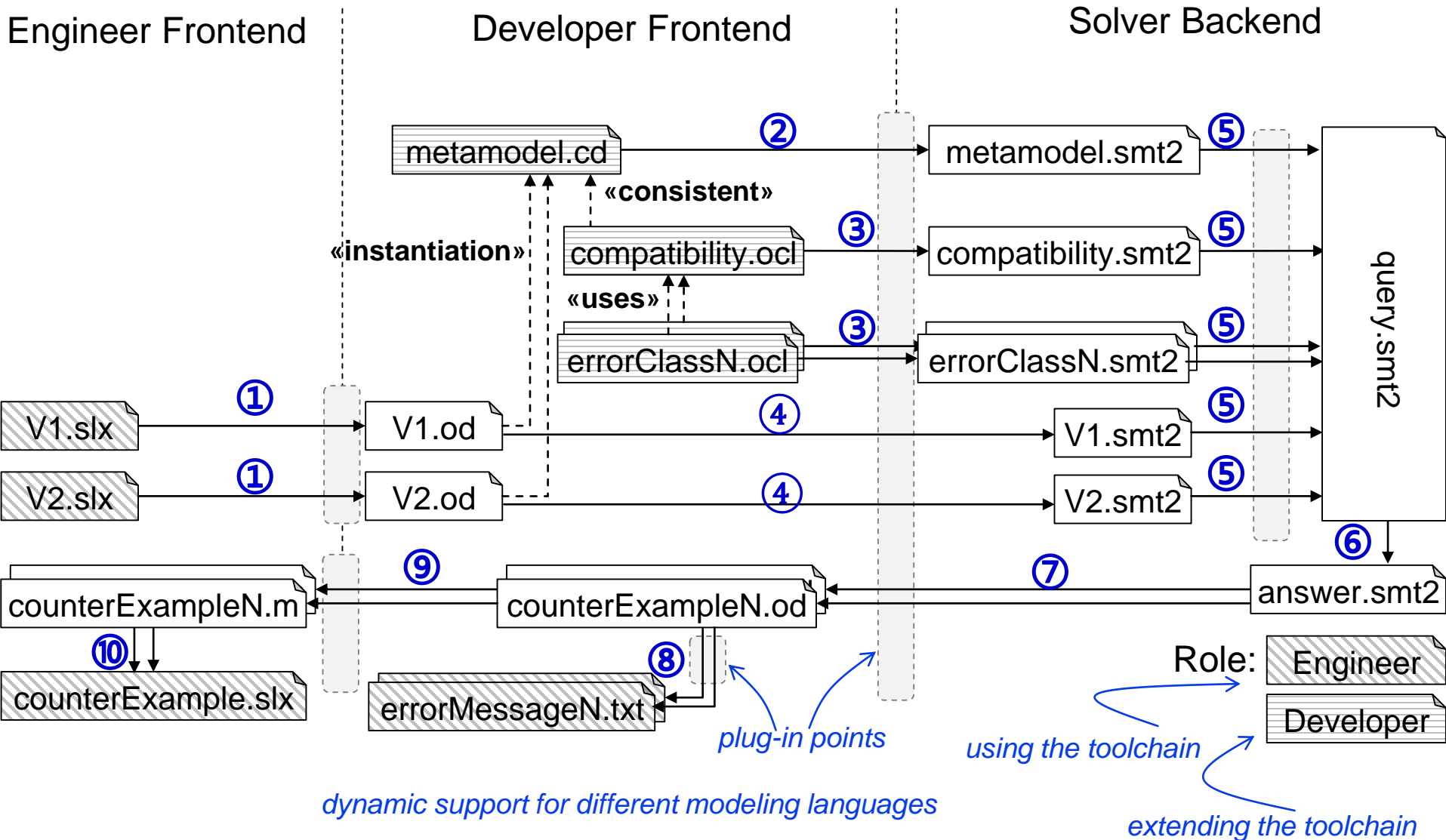
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Extendable Tool Chain - Overview



Syntax example of Z3 and OCL/P

Z3

```
1 (define-fun IsIn_Number_Range ((v Number) (r Range)) Bool
2   (and (GreaterThan_Number_Number v (minimum r))
3     (LessThen_Number_Number v (maximum r))
4     (or (not (resDefined r))
5       (Equals_Number_Number
6         (Mod_Number_Number (Minus_Number_Number v (minimum r))
7           (resolution r))
8         (mk-number 0) )))
```

OCL/P

```
1 def boolean infix (Number v) in (Range r) is:
2   result = v >= r.min && v <= r.max &&
3     (~r.res || (v - range.min) % range.res == 0)
```

OCL/P has a **better understandable** mathematical **infix** notation, while Z3 uses a parenthesized **prefix** notation which is not easy to read and write.

A more complex example, comparing two ADAS, and showing how generated SMT code actually looks like is online available.

<http://rise4fun.com/Z3/2AsLg>

The screenshot shows the Z3 web interface. At the top, it says 'Z3' and 'Research'. Below that, it asks 'Is this formula satisfiable?'. The main area contains SMT code similar to the one shown in the Z3 code block above. At the bottom, there is a navigation bar with buttons for 'tutorial', 'home', 'slides', and 'download'. Below the navigation bar, there is a section titled 'Samples' with a list of examples: 'SMT_ARRAY', 'SMT_ARRAYS', 'SMT_SORT', 'SMT_SORTS', 'SMT_STRINGS', 'SMT_STRINGS', 'SMT_STRINGS', 'SMT_STRINGS', 'SMT_STRINGS', 'SMT_STRINGS'. To the right of the 'Samples' section, there is a section titled 'about Z3 - Efficient Theorem Prover' with a brief description of Z3's capabilities.

Simulation (Preorder) Algorithm

model	time [s]	time* [s]	change in generated Z3 code
m1	timeout	10.08	-
m2	126.68	10.44	remove custom datatypes
m3	93.55	12.86	change encoding of meta-model
m4	138.38	10.47	use <code>ite</code> (if-then-else) instead of <code>implies</code> after quantifier
m5	70.74	8.34	replace enumeration datatypes by integers
m6	19.05	4.33	replace id hash with an unique id starting at zero
m7	15.17	4.23	remove unnecessary <code>ites</code> when translating OCL to Z3

Impact of generated SMT code on Z3's execution time (A = 126 / B = 96)

Z3 ...

```
1 ; meta-model definition
2 (declare-datatypes () ((Connector (mk-connector (source (List Name))
3   (target (List Name)) (id ID))))))
4 ; instance creation
5 (mk-connector (insert n_switch1 (insert n_out1 nil))
6   (insert n_mul (insert n_in2 nil)) id_1593458942)
```

Z3 ...

```
1 (define-fun getConnectorSourceFromId ((id Int)) (List Int)
2 (declare-datatypes () ((Connector (mk-connector (source (List Name))
3   (ite (= id 2) (insert 2 (insert 56 nil))
4   (ite (= id 14) (insert 0 (insert 56 nil))
```

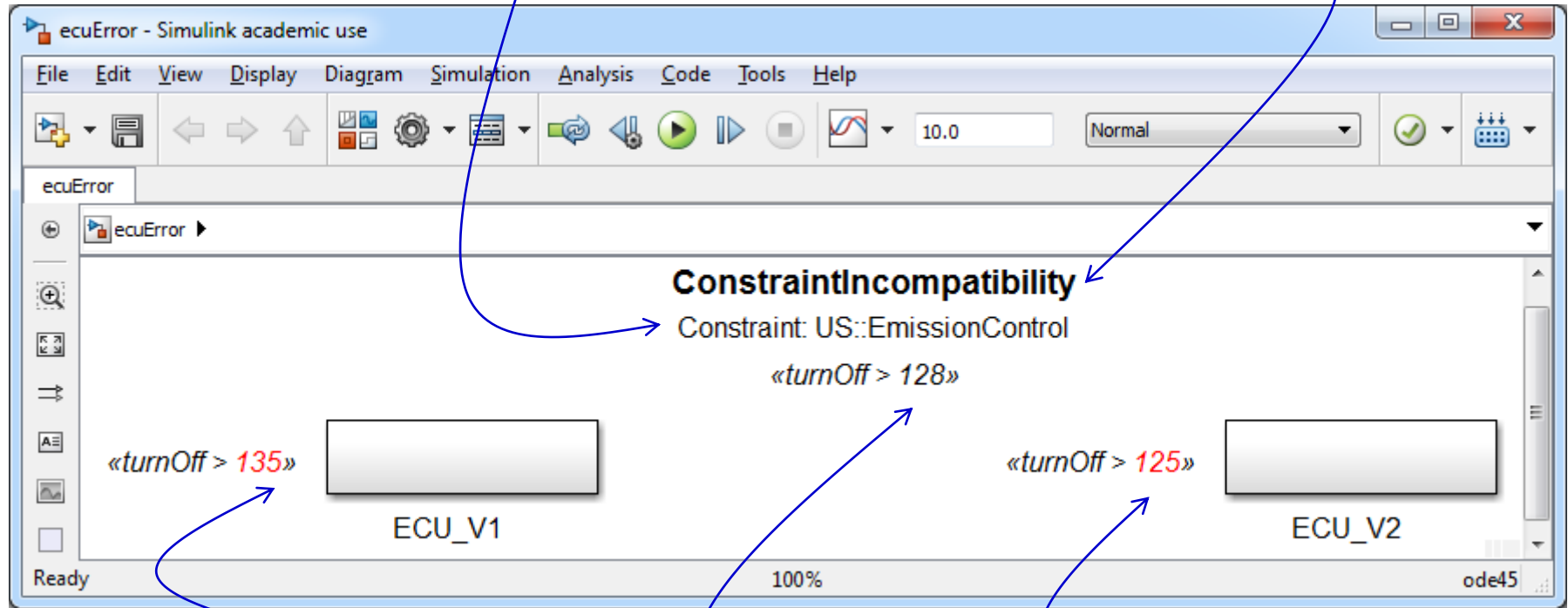
Z3 code used in first version ([top](#)) and last version ([bottom](#))

Counter Example as Simulink Model

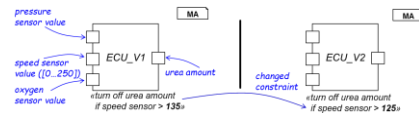
Engineer Fronted

violated constraint

type of incompatibility



backward compatibility
 of ECU V2 to ECU V1



provided counterexample

as no counterexample for
 EU::EmissionControl is provided
 this constraint is not violated

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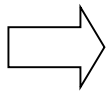
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Conclusion

- **Updates** of software components **are very unpredictable** due to
 - different versions
 - variants
 - and configuration options

- Presentation of a **highly adaptable infrastructure** to check compatibility constraints
 - based on a **generic meta-model** and employs OCL at runtime
 - customizability is achieved via **plug-in points**
 - **different views for developer and engineer** are given inside the presented toolchain
 - since all **transformations are dynamically executed** during the checking process, **redefinitions** and extensions of compatibility definitions and compatibility variations (e.g. for local markets) are **supported**

Conclusion (Requirements from Industry)

- (1) Compatibility constraints should be defined in **comprehensive** and **concise** notation
 - **Usage of OCL/P** instead of **plain solver code** as it is easier to read and understand
 - Feasible, **not too formal** for the developer
 - Introduction of two user types (engineer and developer)

- (2) Method should support **heterogeneous** C&C architecture **models**
 - **Plug-in structure** for use of different modelling languages and solvers
 - Trough **own meta-model** and plugin structure it is **usable for further modeling languages** as the meta-model **is based on an intensive analysis** of well established modeling languages.

Conclusion (Requirements from Industry)

- (3) **Developers** should be able to **modify** structural compatibility constraints at runtime
 - OCL **constraints** can be **added dynamically**
 - 63 constraints have been identified

- (4) **Meaningful** and model related **error messages** for **engineers**
 - **Textual / graphical results** instead of sat / unsat
 - Constructs **counter-example** if not similar

- (5) Genuine C&C model **files** should **not** be **modified**
 - **New m-files are generated** instead of changing the original ones.
 - Textual results presented in **individual files**

Thank you for your attention.